

(Continue)

8/4 ①

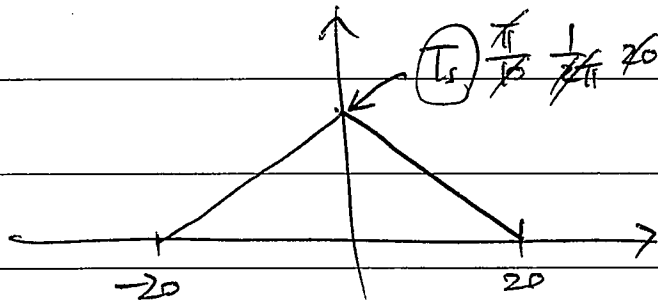
$$x[n] = x_a(nT_s) \quad \text{where } x_a(t) = T_s \frac{\pi}{10} \left( \frac{\sin 10t}{\pi t} \right)^2$$

$$\text{and } T_s = \frac{2\pi}{30} \quad (\omega_s = 30)$$

$$x[n] = \frac{2 \sin\left(\frac{\pi}{6}n\right)}{\pi n} \cos\left(\frac{5\pi}{6}n\right)$$

a) Any aliasing?

First, plot  $|X_a(\omega)|$



$$\text{max freq } (\omega_M) = 20$$

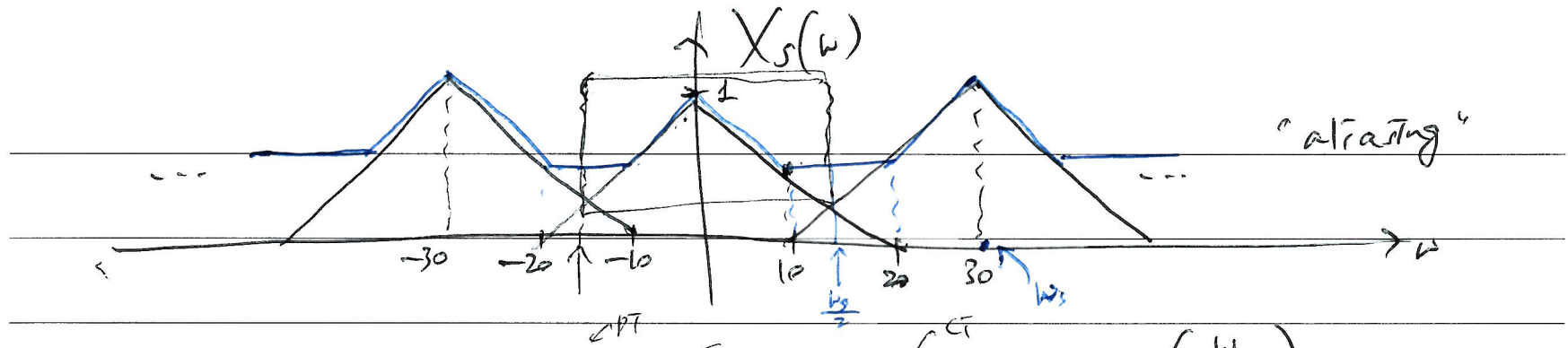
$$\omega_s < 2\omega_M = 2 \cdot 20 \\ (=30)$$

$\Rightarrow$  there is an aliasing.

(not a perfect reconstruction)

b) plot  $|X(\omega)|$  = DTFT of  $x[n]$

$$X_s(\omega) = \mathcal{F} \left\{ \sum_n x_a(nT_s) \delta(t - nT_s) \right\}$$

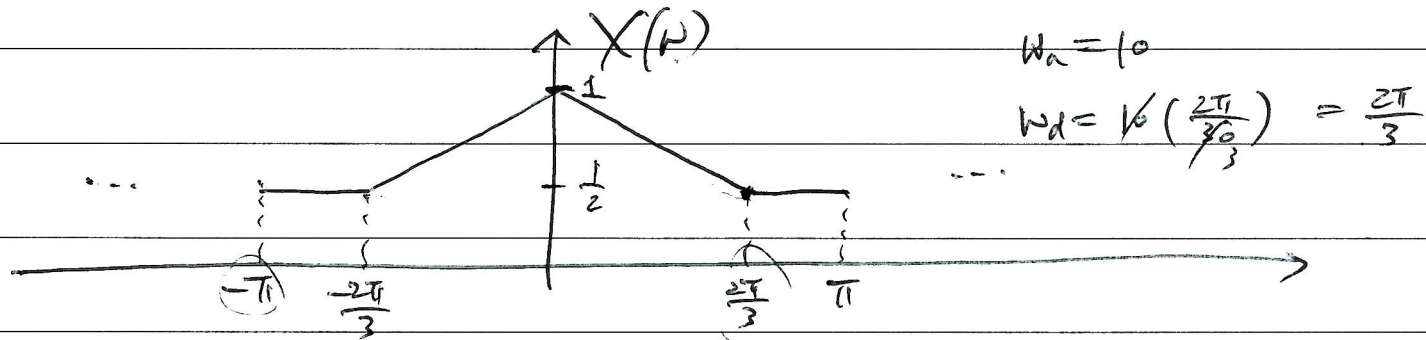


Finally DTFT  $X(\omega) = \sum_{k=-\infty}^{\infty} X_s(\omega - k\omega_s) = X_s\left(\frac{\omega}{T_s}\right)$   $\rightarrow \frac{2\pi}{T_s}$

$\Rightarrow$  map to digital freq via " $\omega_d = \omega T_s$ "

$\Rightarrow$  compress by sampling rate so that

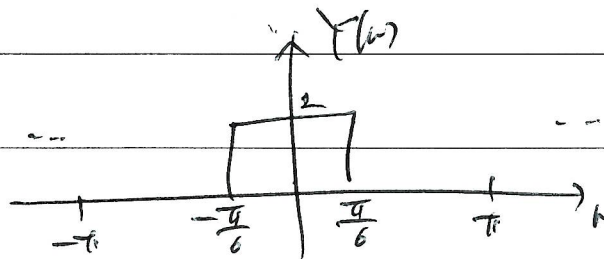
$$-\frac{\omega_s}{2} < \omega_a < \frac{\omega_s}{2} \quad (\text{mapped to}) \quad -\pi < \omega < \pi$$



(c) Plot  $|Y(\omega)|$

$$\frac{\sin(\frac{\pi}{6}n)}{\pi n}$$

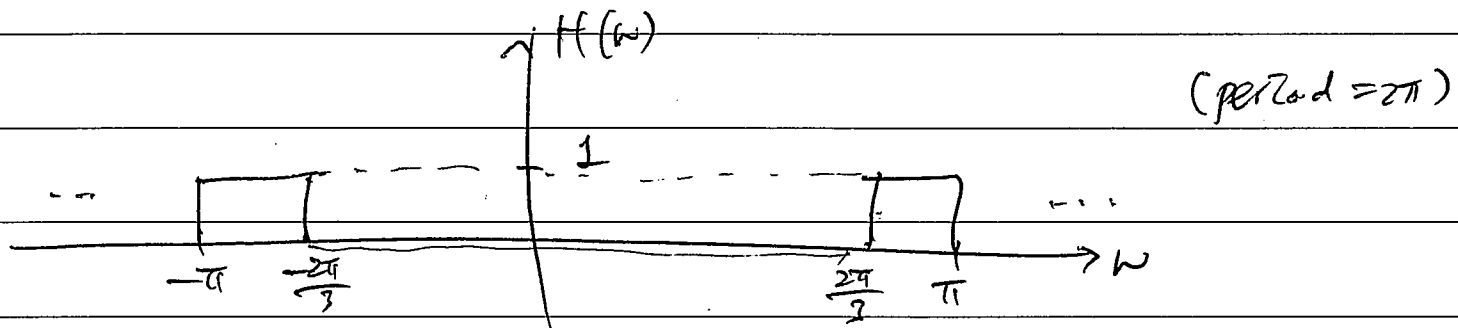
DTFT  $\longleftrightarrow$



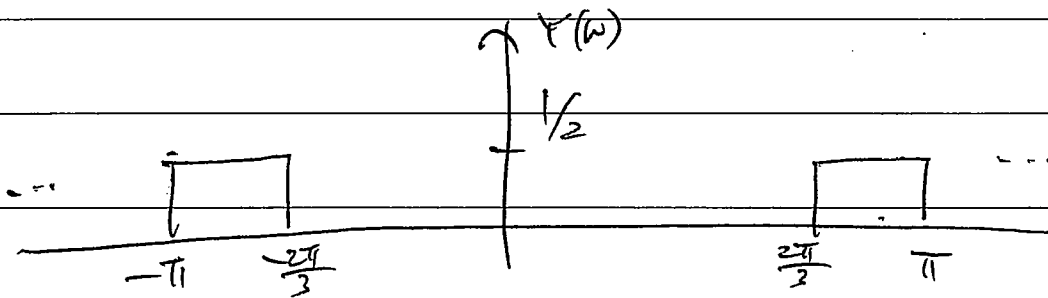
(3)

$$\text{Since } \cos\left(\frac{5\pi}{6}n\right) = \frac{1}{2}e^{j\frac{5\pi}{6}n} + \frac{1}{2}e^{-j\frac{5\pi}{6}n}$$

$$H(\omega) = \text{DTFT} \left\{ \frac{2\sin\left(\frac{\pi}{6}n\right) \cos\left(\frac{5\pi}{6}n\right)}{\pi n} \right\}$$



$$\text{Since } Y(\omega) = H(\omega) X(\omega)$$



$$(d) \sum_n y^2[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} |Y(\omega)|^2 d\omega = \frac{1}{2\pi} \cdot \underbrace{\left(\frac{1}{2}\right)^2}_{\text{height}} \cdot \underbrace{\frac{\pi}{3}}_{\text{width}} = \frac{1}{12}$$

# Chap 10. z-Transform

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$$\text{ZT: } X(z) = \sum_{n=-\infty}^{\infty} x[n] z^{-n}$$

$$\text{DTFT: } X(\omega) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n}$$

$$z = e^{j\omega}$$

$$\begin{array}{ccc} & \nearrow X(z) = z \{x[n]\} & \searrow \\ x[n] & \xleftrightarrow{z} & X(z) \\ & \nwarrow x[n] = z^{-1} \{X(z)\} & \swarrow \end{array}$$

• Linearity :  $z \{ a_1 x_1[n] + a_2 x_2[n] \}$   
 $= a_1 X_1(z) + a_2 X_2(z)$

• Time-shift :  $x[n - n_0] \xleftrightarrow{z} z^{-n_0} X(z)$

• Convolution :  $y[n] = x[n] * h[n] \xleftrightarrow{z} Y(z) = X(z) H(z)$

$$H(z) = \frac{Y(z)}{X(z)} \quad \text{given LTI system}$$

• ZT pair :  $a^n u[n] \xleftrightarrow{z} \frac{z}{z-a}$  , Region of Convergence  $|z| > |a|$

• Time-shift property dictates.

$a^{n-1} u[n-1] \xleftrightarrow{z} z^{-1} \frac{z}{z-a} = \frac{1}{z-a}$  . ROC is same as above.

Comment: Thus, one could use same rules/properties for partial fraction expansion that you learned for LT.

$e^{at} u(t) \xleftrightarrow{L} \frac{1}{s-a}$  vs  $a^{n-1} u[n-1] \xleftrightarrow{z} \frac{1}{z-a}$   
 <CT signal> <DT signal>