

• Freq. response of DT LTI systems described by difference equations.

- Digital filter = difference equation implemented in either software or hardware.
- used to perform freq selective filtering and many other signal processing functions.

< general form of difference eq >

$$\underline{y[n]} = - \sum_{k=1}^N a_k y[n-k] + \sum_{k=0}^M b_k x[n-k]$$

Interested in the freq response of an LTI system (= difference eq), which is the DTFT of the impulse response of the system.

$$\underline{h[n]} \xleftrightarrow{\text{DTFT}} \underline{H(\omega)}$$

- Three properties of DTFT - (linearity, time-shift, convolution - allow us to find $H(\omega)$ without ever determining $h[n]$ (impulse response).

- Take DTFT of both sides of diff. eq. using linearity and time-shift properties.

$$Y(\omega) = - \sum_{k=1}^N a_k e^{-jk\omega} Y(\omega) + \sum_{k=0}^M b_k e^{-jk\omega} X(\omega)$$

$$Y(\omega) \left(1 + \sum_{k=1}^N a_k e^{-jk\omega} \right) = \left(\sum_{k=0}^M b_k e^{-jk\omega} \right) X(\omega)$$

$$Y(\omega) = \left\{ \frac{\sum_{k=0}^M b_k e^{-jk\omega}}{1 + \sum_{k=1}^N a_k e^{-jk\omega}} \right\} X(\omega)$$

<General Info> LTI
($y[n] = h[n] * x[n]$)
($Y(\omega) = H(\omega) X(\omega)$)

$$= H(\omega)$$

$$H(\omega) = \frac{Y(\omega)}{X(\omega)} = \frac{\sum_{k=0}^M b_k e^{-jk\omega}}{1 + \sum_{k=1}^N a_k e^{-jk\omega}} \quad \text{"Frequency Response"}$$

$$\begin{aligned} \downarrow \text{I-DTFT} \\ h[n] &= \frac{\sum_{k=0}^M b_k e^{jk\omega}}{\sum_{k=0}^N a_k e^{jk\omega}}, \quad a_0 = 1 \end{aligned}$$

Example

$$y[n] = y[n-1] + x[n] - x[n-4]$$

$a_1 = -1$ $b_0 = 1$ $b_4 = -1$ $b_1 = b_2 = b_3 = 0$
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(method 1) $H(\omega) = \frac{1 - e^{-j4\omega}}{1 - e^{-j\omega}}$

(method 2) Taking DTFT of the diff eq,

$$Y(\omega) = Y(\omega) e^{j\omega} + X(\omega) - X(\omega) e^{-j4\omega}$$

$$Y(\omega) (1 - e^{-j\omega}) = X(\omega) (1 - e^{-j4\omega})$$

$$H(\omega) = \frac{Y(\omega)}{X(\omega)} = \frac{1 - e^{-j4\omega}}{1 - e^{-j\omega}}$$

• Use "half-angle trick" to evaluate how system responds at different freq.

$$\begin{aligned}
 H(\omega) &= \frac{(e^{j2\omega} - e^{-j2\omega}) e^{-j2\omega}}{(e^{j\frac{\omega}{2}} - e^{-j\frac{\omega}{2}}) e^{-j\frac{\omega}{2}}} \cdot \frac{\frac{1}{2j}}{\frac{1}{2j}} \\
 &= \frac{\sin(2\omega)}{\sin(\frac{\omega}{2})} e^{-j\frac{3}{2}\omega}
 \end{aligned}$$

"DTFT" • compare this with DTFT of $h[n] = \delta[n] - \delta[n-4]$

Prob 5.21 (b) $x[n] = \left(\frac{1}{2}\right)^{-n} u[-n-1] \xleftrightarrow{\text{DTFT}} X(\omega) = ?$

$$= \left(\frac{1}{2}\right)^{-n} u[-(n+1)]$$

$$= \frac{1}{2} \left(\frac{1}{2}\right)^{-(n+1)} u[-(n+1)]$$

Using ① $a^n u[n] \xleftrightarrow{\text{DTFT}} \frac{1}{1 - ae^{-j\omega}}$

② $x[-n] \xleftrightarrow{\text{DTFT}} X(-\omega)$

③ $x[n-n_0] \xleftrightarrow{\text{DTFT}} e^{-j\omega n_0} X(\omega)$

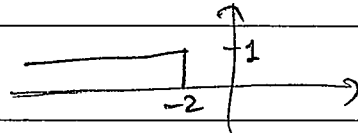
$$X(\omega) \Rightarrow \frac{1}{2} \frac{1}{1 - \frac{1}{2} e^{-j\omega}} e^{-j\omega(-1)}$$

$$\Rightarrow \frac{1}{2} \frac{1}{1 - \frac{1}{2} e^{-j(-\omega)}} e^{-j(-\omega)(-1)}$$

Prob 5.24 (c) $x[n] = \left(\frac{1}{3}\right)^{|n|} u[-n-2] \xleftrightarrow{\text{DTFT}} X(\omega) = ?$

$$= \left(\frac{1}{3}\right)^{|n|} u[-(n+2)]$$

turns on at $n=-\infty$ shuts off at $n=-1$



$$x[n] = \left(\frac{1}{3}\right)^{-n} u[-(n+2)] \quad \text{since } |n| = -n \text{ for } n < 0$$

$$= \left(\frac{1}{3}\right)^2 \left(\frac{1}{3}\right)^{-(n+2)} u[-(n+2)]$$

From the previous problem,

$$X(\omega) = \frac{1}{9} e^{-j\omega(-2)} \frac{1}{1 - \frac{1}{3} e^{-j(\omega)}}$$