Color Seminar

SENSITOMETRY AND THE HUMAN VISUAL SYSTEM

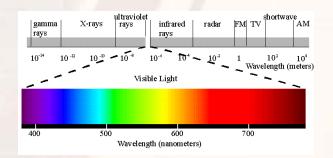




- Basics
 - Spectral Properties
 - Visible spectrum
 - Wavelength range ~ 400-700nm
 - Reflectance
 - Light hits an object, then the eye
 - Perception is relative to a white reference

- Radiance

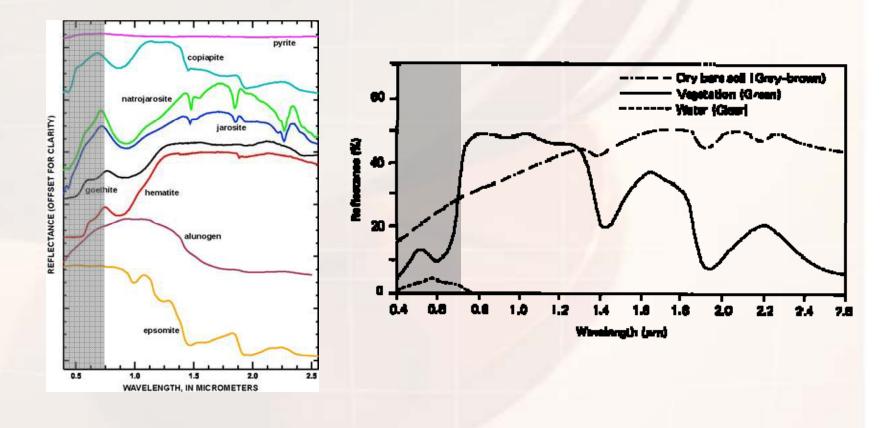
- Emissive device
- Not illuminant dependant







• What does reflectance factor look like?

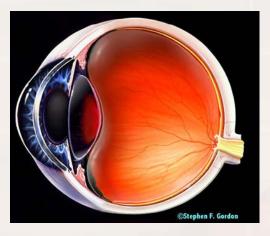




How do we measure color? • Dispersion - Spectral Analysis Angle WHITE Fuji CCD Foveon Tri-linear Bayer **Tri-Chromatic** — Sony RGBE Canon CYGM Nikon D1X Fuji CCD SR Beam Splitter Mark Shaw, Hewlett Packard Company



• The Human Visual System



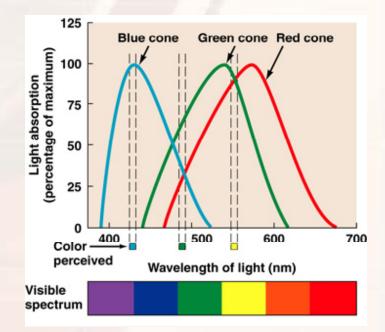
- The eye is an integrator
- Rods vs Cones

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- Scotopic Night vision, only Rods
- Mesopic Dusk vision, both Rods and Cones
- Photopic Day vision, only Cones



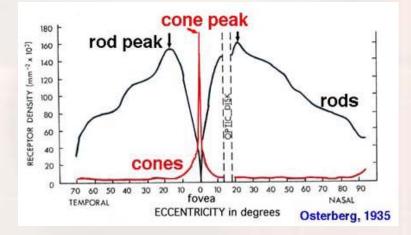


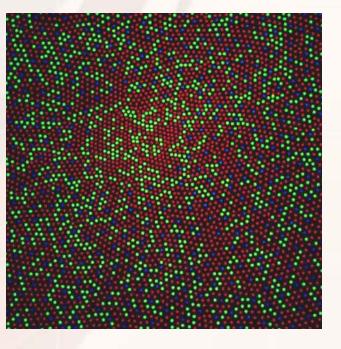
http://www.colorado.edu/intphys/Class/ IPHY3730/image/figure6e.jpg



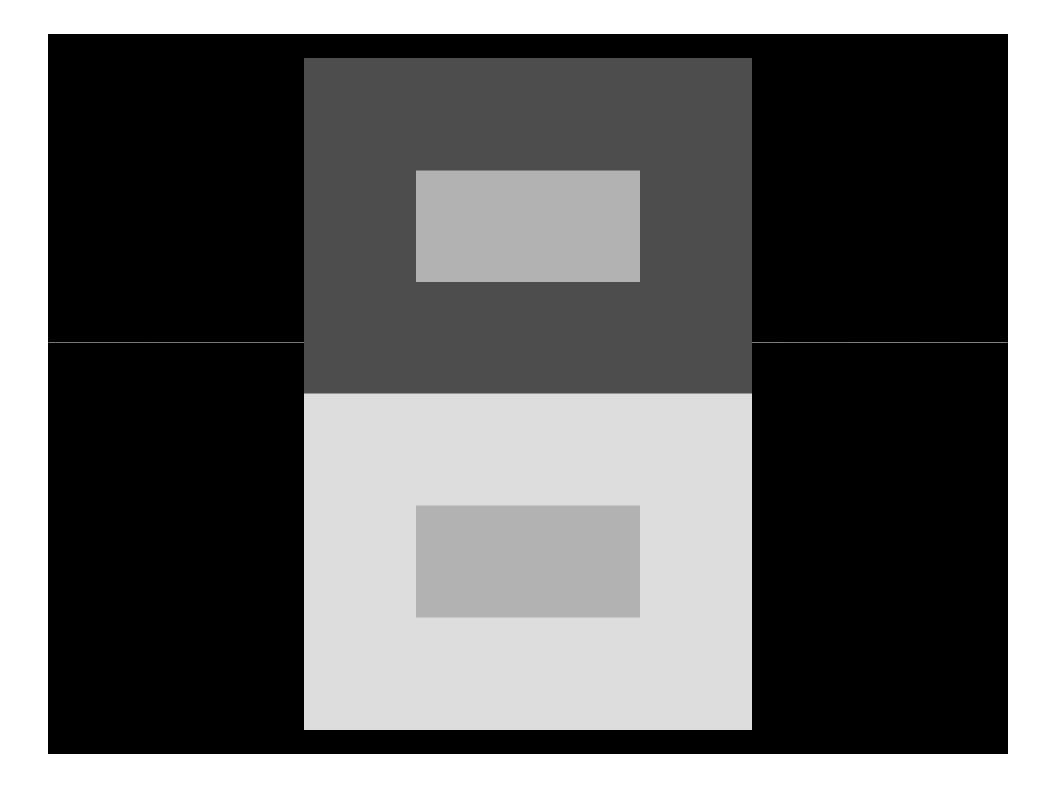
• Not all things are made equal

- Foveal Density
 - 20 L Cones
 - 10 M Cones
 - 1 S Cones





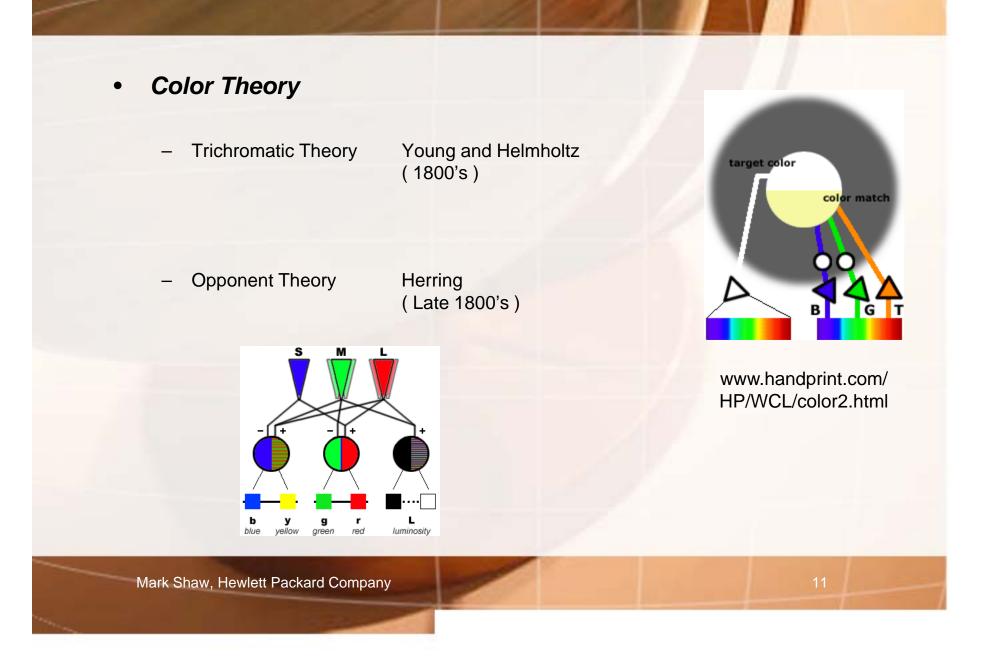
http://www.beercolor.com/color_basics1_files /image005.jpg



Color Constancy Demo

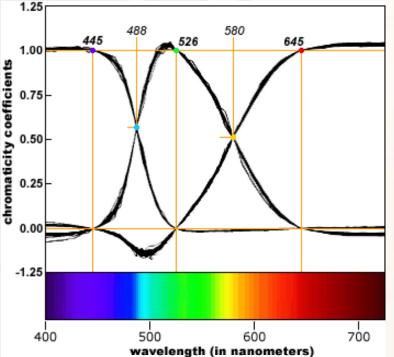
COLOR THEORY





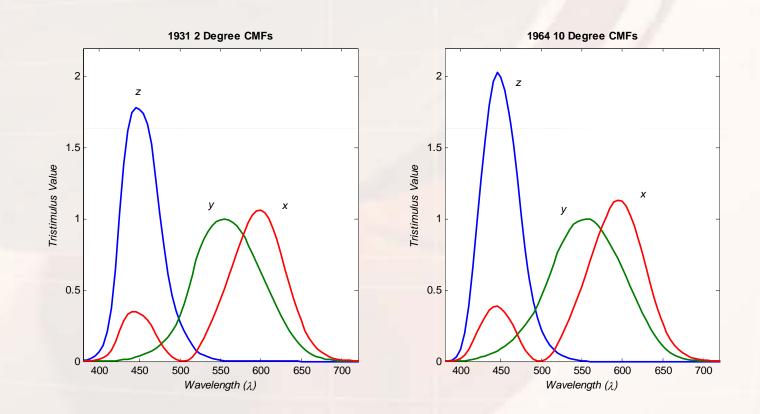


- Color Matching
 - How do we get a color match?
 - Subjectively
 - Quantatively
 - Every observer is slightly different
 - Work of Wright and Guild (1920's)
 - Achromatic mixing experiment
 - Negative lobes occurred because the third primary was needed in order to make a match, that primary essentially acts as a subtraction





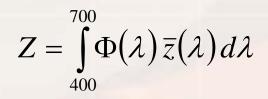
• CIE Color Matching Functions (1931 2° Observer and 1964 10° Observer)





$$X = \int_{400}^{700} \Phi(\lambda) \,\overline{x}(\lambda) \, d\lambda$$

$$Y = \int_{400}^{700} \Phi(\lambda) \,\overline{y}(\lambda) \, d\lambda$$



Reflectance

$$\Phi = S(\lambda) R(\lambda)$$

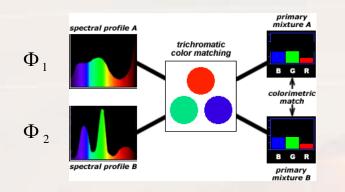
S is the illuminant spectra R is the reflectance factor of the object Radiance

$$\Phi = L(\lambda)$$
 or $E(\lambda)$

L is the Luminosity, also called E (Emittance)



• A colorimetric match if ...



the tristimulus values match under specific conditions.

$$X_{1} = X_{2}$$

$$\int_{400}^{700} \Phi_{1}(\lambda) \,\overline{x}(\lambda) \, d\lambda = \int_{400}^{700} \Phi_{2}(\lambda) \,\overline{x}(\lambda) \, d\lambda$$

$$Y_1 = Y_2$$

$$\int_{00}^{00} \Phi_1(\lambda) \,\overline{y}(\lambda) \, d\lambda = \int_{400}^{700} \Phi_2(\lambda) \,\overline{y}(\lambda) \, d\lambda$$

$$Z_{1} = Z_{2}$$

$$\int_{00}^{00} \Phi_{1}(\lambda) \,\overline{z}(\lambda) \, d\lambda = \int_{400}^{700} \Phi_{2}(\lambda) \,\overline{z}(\lambda) \, d\lambda$$



- What does it mean if ...

$$\int_{400}^{700} S_1(\lambda) R_1(\lambda) \overline{x}(\lambda) d\lambda = \int_{400}^{700} S_1(\lambda) R_2(\lambda) \overline{x}(\lambda) d\lambda$$

but
$$\int_{400}^{700} S_2(\lambda) R_1(\lambda) \overline{x}(\lambda) d\lambda \neq \int_{400}^{700} S_2(\lambda) R_2(\lambda) \overline{x}(\lambda) d\lambda$$

we have a metameric match under S_1 but not under S_2

Observer Metamerism

- When two colors match for one observer but not for another
- Color blindness is one example

Illuminant Metamerism

- Two samples match under one light source, but not another



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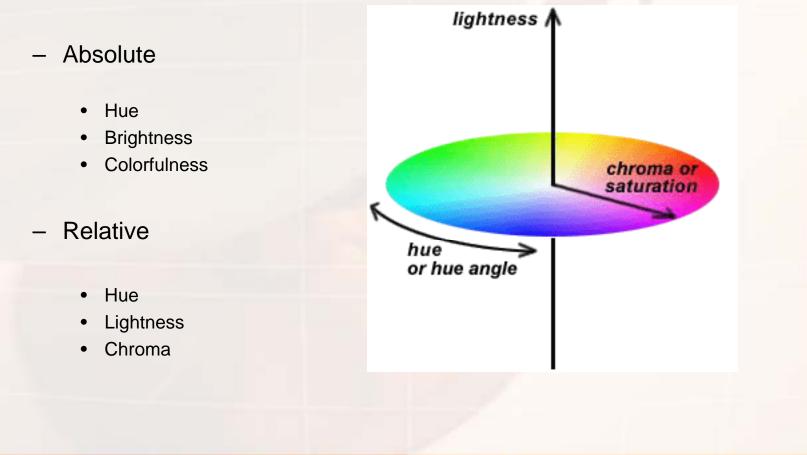
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COLOR APPEARANCE





Color Appearance Modeling



- CIE 1976 (L*a*b*) Color Space - aka CIELAB

$$L^{*} = 116 \left(\frac{Y}{Y_{n}}\right)^{\frac{1}{3}} - 16$$
$$a^{*} = 500 \left[\left(\frac{X}{X_{n}}\right)^{\frac{1}{3}} - \left(\frac{Y}{Y_{n}}\right)^{\frac{1}{3}} \right]$$
$$b^{*} = 200 \left[\left(\frac{Y}{Y_{n}}\right)^{\frac{1}{3}} - \left(\frac{Z}{Z_{n}}\right)^{\frac{1}{3}} \right]$$

Opponent Signals

$$X_{n} = \int_{400}^{700} S(\lambda) \,\overline{x}(\lambda) \, d\lambda$$
$$Y_{n} = \int_{400}^{700} S(\lambda) \,\overline{y}(\lambda) \, d\lambda$$
$$Z_{n} = \int_{400}^{700} S(\lambda) \,\overline{z}(\lambda) \, d\lambda$$

 $X_n Y_n Z_n$ are the tristimulus values of the white point



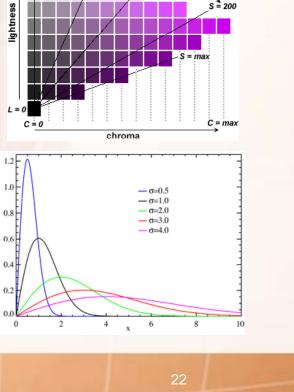
- Converting Cartesian co-ordinates into a Polar space

 $L^* = L^*$ $C^* = \sqrt{\left(a^*\right)^2 + \left(b^*\right)^2}$ $h_{ab}^* = \tan^{-1}\left(\frac{b^*}{a^*}\right)$

Calculating Color Differences

$$\Delta E_{76} = \sqrt{(\Delta L^{*})^{2} + (\Delta a^{*})^{2} + (\Delta b^{*})^{2}}$$

Color differences are not normally distributed



^{.saturation}.

S = 100

S = 50

hue = red violet

s =

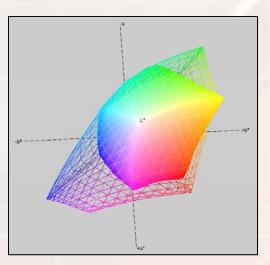
L=100

COLOR MODELING





- How does one map colors between devices?
 - First one must build colorimetric models of the source and destination devices

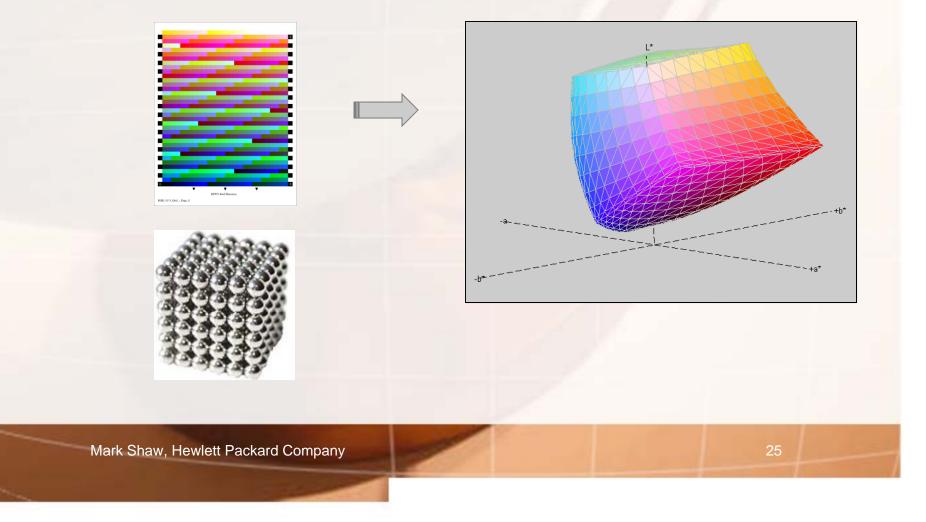


The range of colors the device can create is called the "Color Gamut"

- Then one must map all colors from the source gamut to the destination gamut

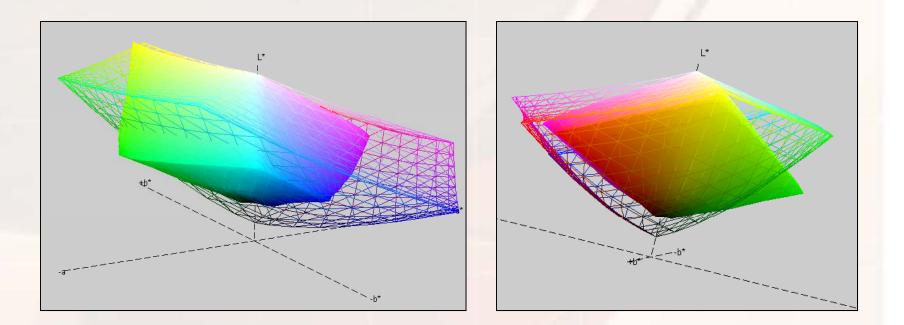


• How does one build a model of a device?

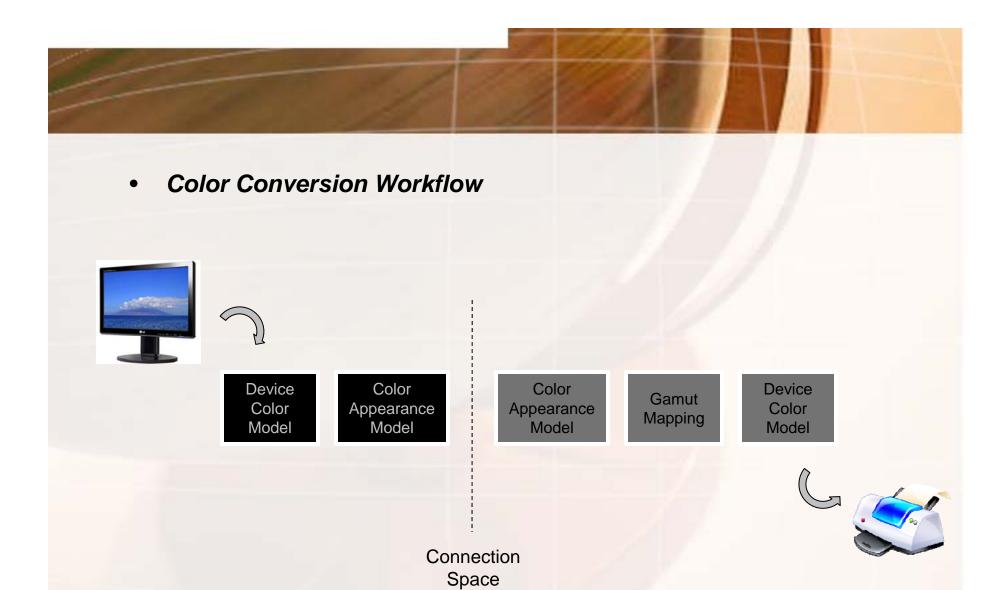




• Comparing Device Gamuts



The process of mapping colors from one device to another is called *Gamut Mapping*



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SUMMARY



- The Human Visual System is an integrator
- A colorimetric match only holds if the viewing conditions remain unchanged
- Metamerism is a very important concept
 - Most current imaging systems rely upon the a metameric match
 - Spectral matches would be ideal, but are currently prevented by technological limitations
- Color appearance models enable the communication of color in meaningful terms
- Color Modeling enables one to communicate color consistently