

(22 pts) 1. Let  $x(t)$  and  $y(t)$  be the input and the output of a continuous-time system, respectively. Answer each of the questions below with either yes or no (no justification needed).

	Yes	No
If $y(t) = x(2t)$ , is the system causal?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
If $y(t) = (t + 2)x(t)$ , is the system causal?	<input type="checkbox"/>	<input checked="" type="checkbox"/> <del>X</del>
<i>choose <math>t = -\frac{1}{2}</math></i> If $y(t) = x(-t^2)$ , is the system causal?	<input checked="" type="checkbox"/>	<input type="checkbox"/> <del>X</del>
If $y(t) = x(t) + t - 1$ , is the system memoryless?	<input checked="" type="checkbox"/>	<input type="checkbox"/>
If $y(t) = x(t^2)$ , is the system memoryless?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
If $y(t) = x(t/3)$ , is the system stable?	<input checked="" type="checkbox"/>	<input type="checkbox"/>
If $y(t) = tx(t/3)$ , is the system stable?	<input type="checkbox"/>	<input checked="" type="checkbox"/>
If $y(t) = \int_{-\infty}^t x(\tau)d\tau$ , is the system stable?	<input type="checkbox"/>	<input checked="" type="checkbox"/> <del>X</del>
If $y(t) = \sin(x(t))$ , is the system time invariant?	<input type="checkbox"/>	<input checked="" type="checkbox"/> <del>X</del>
If $y(t) = u(t) * x(t)$ , is the system LTI?	<input checked="" type="checkbox"/>	<input type="checkbox"/>
If $y(t) = \underline{tu(t)} * x(t)$ , is the system linear?	<input type="checkbox"/>	<input checked="" type="checkbox"/> <del>X</del>

*b/c convolution is linear*

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(15 pts) 2. An LTI system has unit impulse response  $h(t) = u(t+2)$ . Compute the system's response to the input  $x(t) = e^{-t}u(t)$ . (Simplify your answer until all  $\sum$  signs disappear.)

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$y(t) = \int_{-\infty}^{\infty} e^{-\tau} u(\tau) u(t+2-\tau) d\tau$$

$$u(\tau) = 0 \text{ for } \tau < 0 \Rightarrow y(t) = \int_0^{\infty} e^{-\tau} u(t+2-\tau) d\tau$$

$$u(t+2-\tau) = 0 \text{ for } \tau > t+2 \Rightarrow y(t) = \int_0^{t+2} e^{-\tau} d\tau \quad \#$$

$$y(t) = -e^{-\tau} \Big|_0^{t+2} = -(e^{-(t+2)} - e^0)$$

$$y(t) = 1 - e^{-(t+2)}$$

~~No~~  
 ~~$P_{av} = \lim_{T \rightarrow \infty} \frac{E_{av}}{2T}$~~

~~02~~

(15 pts) 3. Compute the energy and the power of the signal  $x(t) = \frac{3e^{jt}}{1+j}$ .

$$x(t) = \frac{3e^{jt}}{1+j}$$

$$E_{\infty} = \int_{-\infty}^{\infty} |x(t)|^2 dt = \int_{-\infty}^{\infty} \left| \frac{3e^{jt}}{1+j} \right|^2 dt \rightarrow \frac{3}{1+j} (e^{jt}) \Rightarrow \frac{3}{1+j} (\cos t + j \sin t)$$

$$\rightarrow \frac{3(1-j)}{(1+j)(1-j)} (\cos t + j \sin t) = \frac{3-3j}{2} (\cos t + j \sin t) \quad \text{take Real} \quad \text{No}$$
$$\Leftrightarrow \frac{3}{2} \cos t + \frac{3}{2} \sin t$$

$$E_{\infty} = \int_{-\infty}^{\infty} \left| \frac{3}{2} (\cos t + \sin t) \right|^2 dt = \frac{9}{4} \int_{-\infty}^{\infty} 1 dt$$

$$~~P_{av} = \lim_{T \rightarrow \infty} \frac{E_{av}}{2T} = \lim_{T \rightarrow \infty} \frac{\frac{9}{4}}{2T} = \lim_{T \rightarrow \infty} \frac{9}{8T} = \frac{9}{8(\infty)} = 0~~$$

$$E_{\infty} = \frac{9}{4} \quad P_{av} = 0$$

(15 pts) 4. Compute the coefficients  $a_k$  of the Fourier series of the signal  $x(t)$  periodic with period  $T=4$  defined by

$$x(t) = \begin{cases} \sin(\pi t), & 0 \leq t \leq 2 \\ 0, & 2 < t \leq 4 \end{cases}$$

$$\omega_0 = \frac{2\pi}{T} = \frac{2\pi}{4} = \frac{\pi}{2}$$

4 '0k's?

(Simplify your answer as much as possible.)

$$\sin(\pi t) \Rightarrow \frac{e^{j\pi t} - e^{-j\pi t}}{2j} = \left( \frac{1}{2j} e^{j\pi t} - \frac{1}{2j} e^{-j\pi t} \right)$$

$$a_k = \frac{1}{4} \int_0^4 x(t) e^{-jk(\frac{\pi}{2})t} dt = \frac{1}{4} \left( \int_0^2 (\sin(\pi t)) e^{-jk\frac{\pi}{2}t} dt + \int_2^4 0 e^{-jk\frac{\pi}{2}t} dt \right)$$

$$a_k = \frac{1}{4} \int_0^2 \left( \frac{1}{2j} e^{j\pi t} - \frac{1}{2j} e^{-j\pi t} \right) e^{-jk\frac{\pi}{2}t} dt = \frac{1}{8j} \int_0^2 (e^{j\pi t} - e^{-j\pi t}) e^{-jk\frac{\pi}{2}t} dt$$

$$a_0 = \frac{1}{8j} \int_0^2 (e^{j\pi t} - e^{-j\pi t}) e^0 dt = \frac{1}{8j} \left( \frac{1}{\pi} (e^{j2\pi} - 1) + (e^{j2\pi} - 1) \right)$$

$$a_0 = \frac{1}{4\pi j} (e^{j2\pi} - 1)$$

$$a_1 = \frac{1}{8j} \int_0^2 (e^{j\pi t} - e^{-j\pi t}) e^{-j\frac{\pi}{2}t} dt = \frac{1}{8j} \int_0^2 (e^{j\frac{\pi}{2}t} - e^{-j\frac{3\pi}{2}t}) dt$$

$$a_1 = \frac{1}{8j} \left( \frac{2}{\pi} (e^{j\pi} - 1) - \left( -\frac{2}{3\pi} (e^{-j3\pi} - 1) \right) \right) = \frac{1}{8j} \left( \frac{2}{\pi} e^{j\pi} - \frac{2}{\pi} + \frac{2}{3\pi} e^{-j3\pi} - \frac{2}{3\pi} \right)$$

$$a_1 = \frac{1}{8j} \left( \frac{2}{\pi} e^{j\pi} + \frac{2}{3\pi} e^{-j3\pi} + \frac{4}{3\pi} \right)$$

$$a_{-1} = \frac{1}{8j} \int_0^2 (e^{j\pi t} - e^{-j\pi t}) e^{+j\frac{\pi}{2}t} dt = \frac{1}{8j} \int_0^2 (e^{j\frac{3\pi}{2}t} - e^{-j\frac{\pi}{2}t}) dt$$

$$a_{-1} = \frac{1}{8j} \left( \frac{2}{3\pi} e^{3\pi} + \frac{2}{\pi} e^{j\pi} - \frac{4}{3\pi} \right)$$

$$a_2 = \frac{1}{8j} \int_0^2 (e^{j\pi t} - e^{-j\pi t}) e^{-j2\pi t} dt = \frac{1}{8j} \int_0^2 (0 - e^{-j\pi t}) dt = \frac{1}{8j} \left( -\frac{1}{\pi} (e^{-j4\pi} - 1) \right)$$

$$a_2 = -\frac{1}{16j} (e^{-j4\pi} - 1)$$

5. A discrete-time system is such that when the input is one of the signals in the left column, then the output is the corresponding signal in the right column:

input	output
$x_0[n] = \delta[n]$	$\rightarrow y_0[n] = \delta[n - 1],$
$x_1[n] = \delta[n - 1]$	$\rightarrow y_1[n] = 4\delta[n - 2],$
$x_2[n] = \delta[n - 2]$	$\rightarrow y_2[n] = 9\delta[n - 3],$
$x_3[n] = \delta[n - 3]$	$\rightarrow y_3[n] = 16\delta[n - 4],$
$\vdots$	
$x_k[n] = \delta[n - k]$	$\rightarrow y_k[n] = (k + 1)^2\delta[n - (k + 1)]$ for any integer $k.$

(10 pts) a) Can this system be time-invariant? Explain.

○  $x_2[n - n_0] = \delta[n - n_0 - 2] \Rightarrow y_2[n - n_0] = 9\delta[n - n_0 - 3]$

Let  $n_0 = 3$

$x_2[n - 3] = \delta[n - 5] \Rightarrow y_2[n - 3] = 9\delta[n - 5]$

original  $x_2[n]$  equation required  $n = 2$  for  $y_2[n] \neq 0$  b/c of  $\delta[n - 2]$ ,  
with  $n_0 = 3$ ,  $n$  now has to be  $5$  for  $y_2[n] \neq 0$ . So  $y_2[5 - 3] = y_2[2]$  yes TI.

(10 pts) b) Assuming that this system is linear, what input  $x[n]$  would yield the output  $y[n] = u[n - 1]$ ?

~~$u[n - 1] = \sum_{-\infty}^{\infty} \delta[n - 1 - k] x[k]$~~

~~$u[n - 1] = 0$  for  $n < 1$~~

~~$= 1$  for  $n \geq 1$~~

~~$x_0[n] = \delta[n] \Rightarrow y_0[n] = \delta[n - 1]$~~

~~$x[n] = u[n]$~~  :(