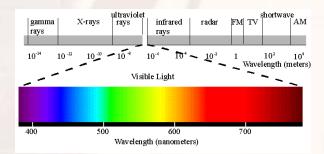


SENSITOMETRY AND THE HUMAN VISUAL SYSTEM

• Basics

- Spectral Properties
 - Visible spectrum
 - Wavelength range ~ 400-700nm



- Reflectance

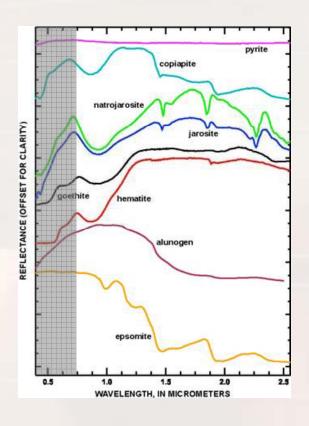
- Light hits an object, then the eye
- Perception is relative to a white reference

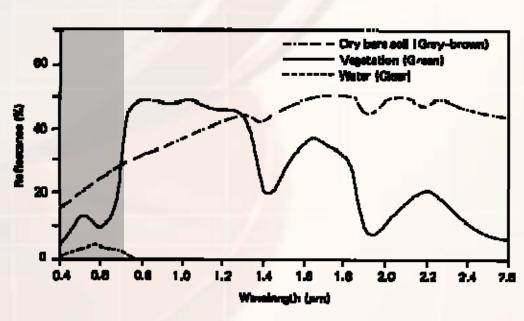
- Radiance

- Emissive device
- Not illuminant dependant



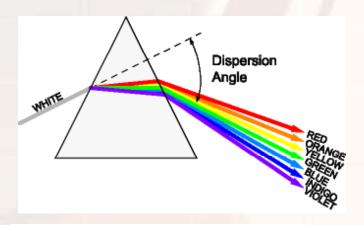
• What does reflectance factor look like?

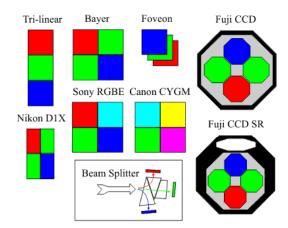




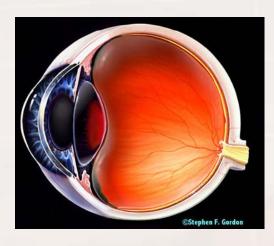
- How do we measure color?
 - Spectral Analysis

- Tri-Chromatic

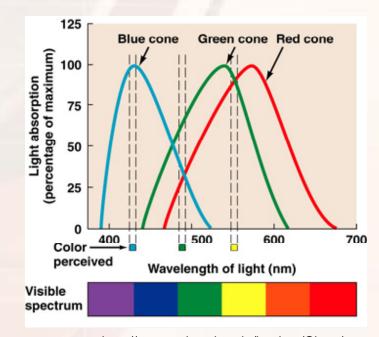




• The Human Visual System



- The eye is an integrator
- Rods vs Cones
 - Scotopic Night vision, only Rods
 - Mesopic Dusk vision, both Rods and Cones
 - Photopic Day vision, only Cones

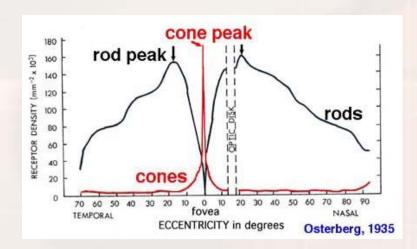


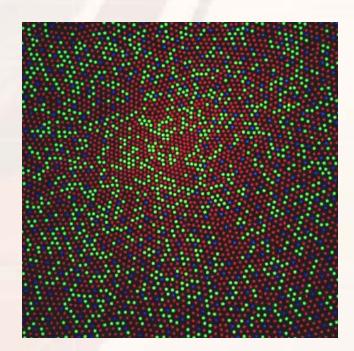
http://www.colorado.edu/intphys/Class/ IPHY3730/image/figure6e.jpg

Not all things are made equal

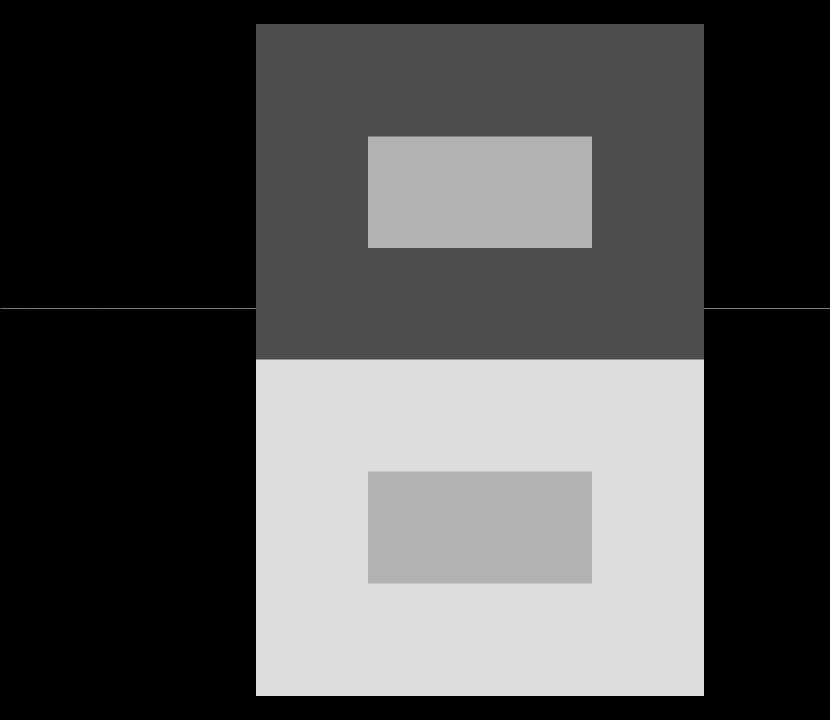
Foveal Density

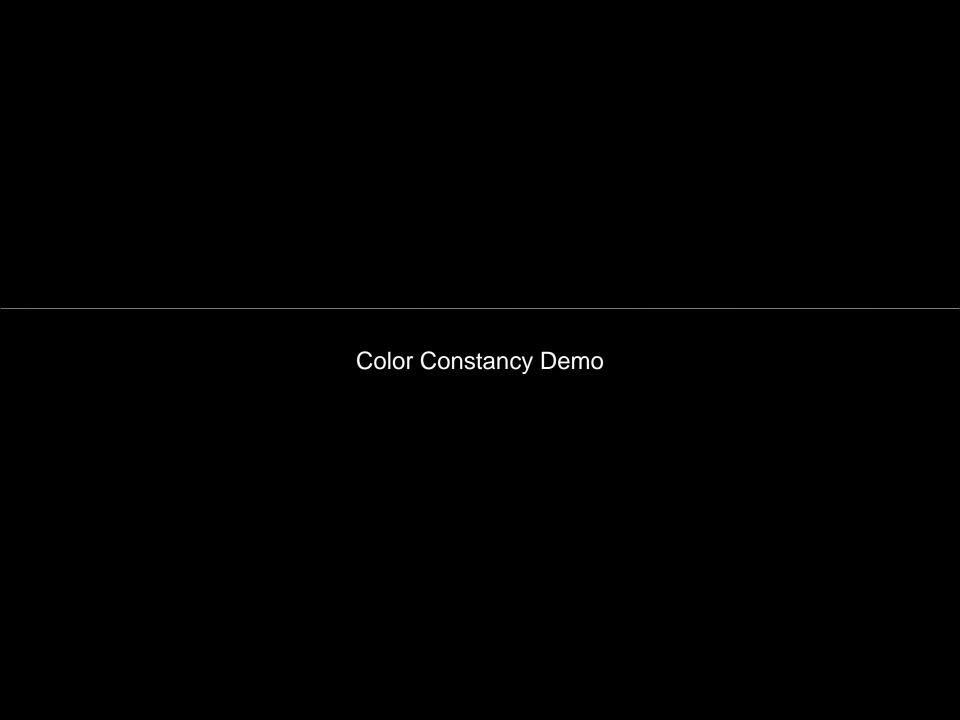
- 20 L Cones
- 10 M Cones
- 1 S Cones

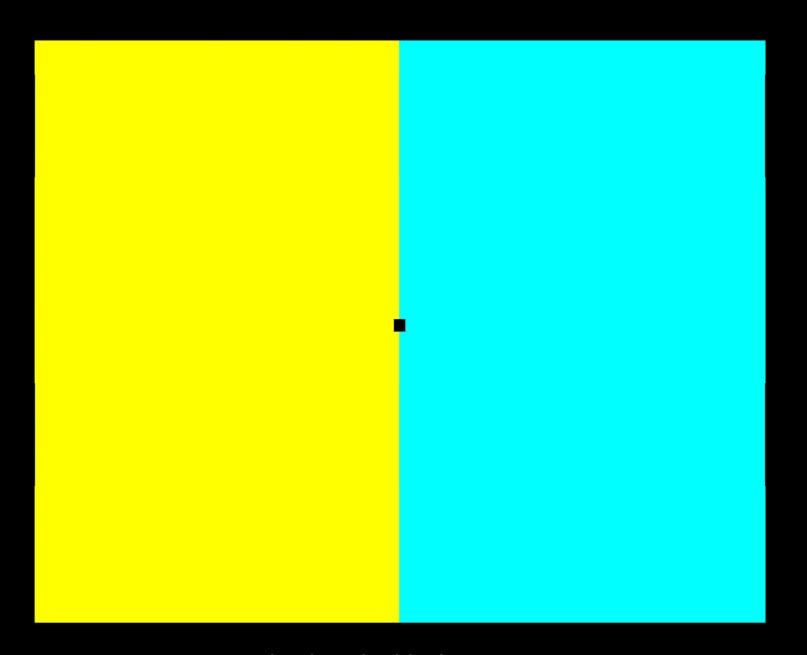




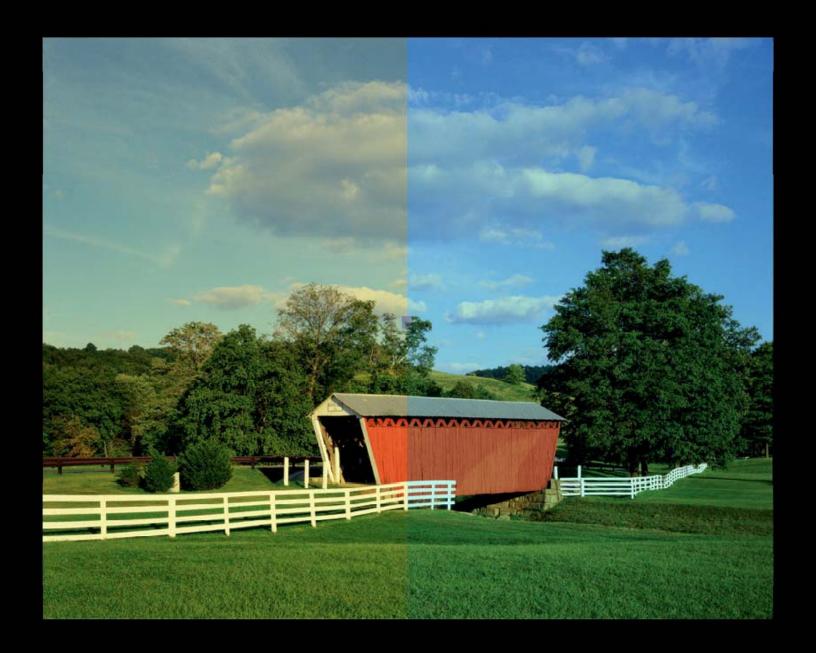
http://www.beercolor.com/color_basics1_files /image005.jpg







Look at the black square





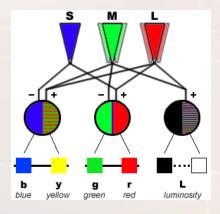


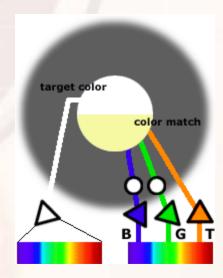
• Color Theory

Trichromatic Theory Young and Helmholtz (1800's)

Opponent Theory

Herring (Late 1800's)

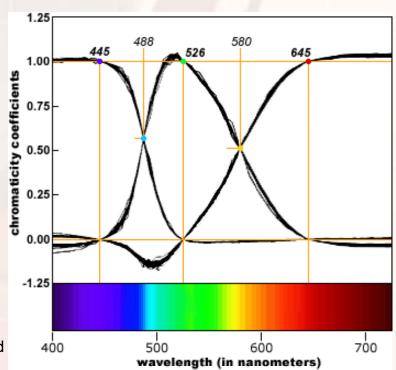




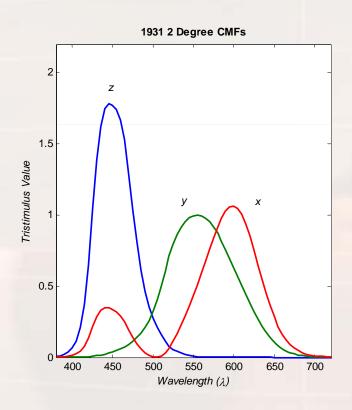
www.handprint.com/ HP/WCL/color2.html

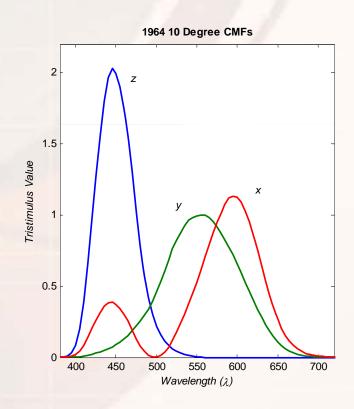
• Color Matching

- How do we get a color match?
 - Subjectively
 - Quantatively
- Every observer is slightly different
 - Work of Wright and Guild (1920's)
 - Achromatic mixing experiment
 - Negative lobes occurred because the third primary was needed in order to make a match, that primary essentially acts as a subtraction



• CIE Color Matching Functions (1931 2º Observer and 1964 10º Observer)





$$X = \int_{400}^{700} \Phi(\lambda) \, \overline{x}(\lambda) \, d\lambda \qquad Y = \int_{400}^{700} \Phi(\lambda) \, \overline{y}(\lambda) \, d\lambda$$

$$Y = \int_{400}^{700} \Phi(\lambda) \, \overline{y}(\lambda) \, d\lambda$$

$$Z = \int_{400}^{700} \Phi(\lambda) \, \overline{z}(\lambda) \, d\lambda$$

Reflectance

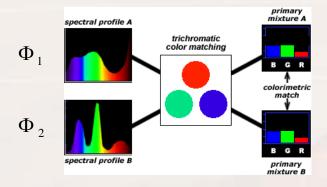
$$\Phi = S(\lambda) R(\lambda)$$

S is the illuminant spectra R is the reflectance factor of the object Radiance

$$\Phi = L(\lambda)$$
 or $E(\lambda)$

L is the Luminosity, also called E (Emittance)

• A colorimetric match if ...



the tristimulus values match under specific conditions.

$$X_{1} = X_{2}$$

$$\int_{400}^{700} \Phi_{1}(\lambda) \overline{x}(\lambda) d\lambda = \int_{400}^{700} \Phi_{2}(\lambda) \overline{x}(\lambda) d\lambda$$

$$Y_{1} = Y_{2}$$

$$\int_{400}^{700} \Phi_{1}(\lambda) \, \overline{y}(\lambda) \, d\lambda = \int_{400}^{700} \Phi_{2}(\lambda) \, \overline{y}(\lambda) \, d\lambda$$

$$Z_{1} = Z_{2}$$

$$\int_{400}^{700} \Phi_{1}(\lambda) \overline{z}(\lambda) d\lambda = \int_{400}^{700} \Phi_{2}(\lambda) \overline{z}(\lambda) d\lambda$$

• Metamerism

- What does it mean if ...

$$\int_{400}^{700} S_{1}(\lambda) R_{1}(\lambda) \overline{x}(\lambda) d\lambda = \int_{400}^{700} S_{1}(\lambda) R_{2}(\lambda) \overline{x}(\lambda) d\lambda$$

$$but$$

$$\int_{400}^{700} S_{2}(\lambda) R_{1}(\lambda) \overline{x}(\lambda) d\lambda \neq \int_{400}^{700} S_{2}(\lambda) R_{2}(\lambda) \overline{x}(\lambda) d\lambda$$

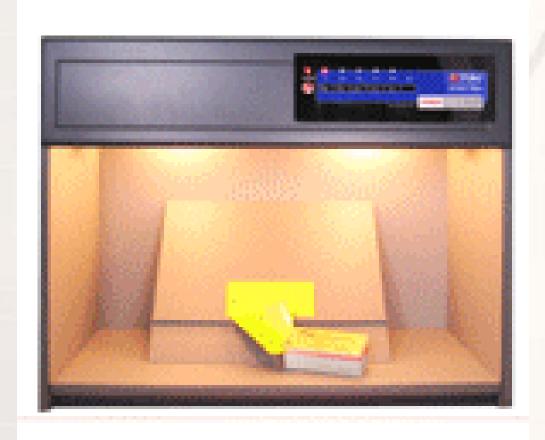
we have a metameric match under S_1 but not under S_2

• Observer Metamerism

- When two colors match for one observer but not for another
- Color blindness is one example

• Illuminant Metamerism

Two samples match under one light source, but not another

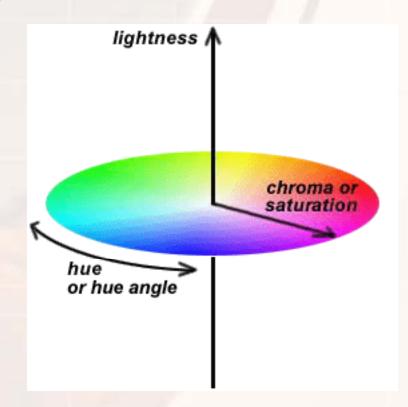


 $http://tqc.eu/images/products/150x150/colorbox_lightsources_animation.gif$



• Color Appearance Modeling

- Absolute
 - Hue
 - Brightness
 - Colorfulness
- Relative
 - Hue
 - Lightness
 - Chroma



CIE 1976 (L*a*b*) Color Space - aka CIELAB

$$L^* = 116 \left(\frac{Y}{Y_n} \right)^{\frac{1}{3}} - 16$$

$$a^* = 500 \left[\left(\frac{X}{X_n} \right)^{\frac{1}{3}} - \left(\frac{Y}{Y_n} \right)^{\frac{1}{3}} \right]$$

$$b^* = 200 \left[\left(\frac{Y}{Y_n} \right)^{\frac{1}{3}} - \left(\frac{Z}{Z_n} \right)^{\frac{1}{3}} \right]$$

X_n Y_n Z_n are the tristimulus values of the white point

Converting Cartesian co-ordinates into a Polar space

$$L^* = L^*$$

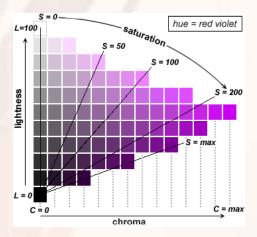
$$C^* = \sqrt{(a^*)^2 + (b^*)^2}$$

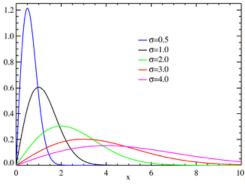
$$h_{ab}^* = \tan^{-1} \left(\frac{b^*}{a^*}\right)$$

Calculating Color Differences

$$\Delta E_{76} = \sqrt{(\Delta L^*)^2 + (\Delta a^*)^2 + (\Delta b^*)^2}$$

Color differences are not normally distributed

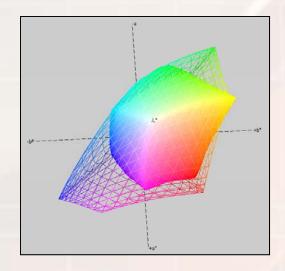






• How does one map colors between devices?

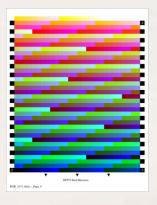
First one must build colorimetric models of the source and destination devices



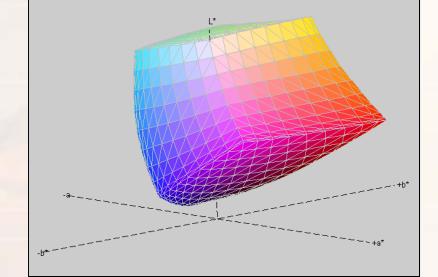
The range of colors the device can create is called the "Color Gamut"

- Then one must map all colors from the source gamut to the destination gamut

• How does one build a model of a device?

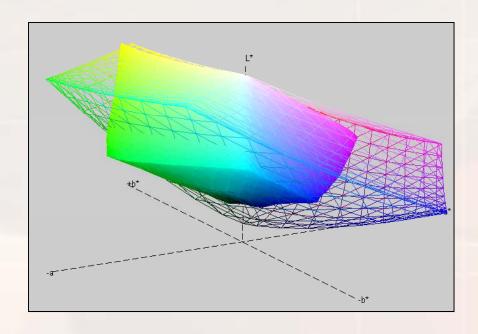


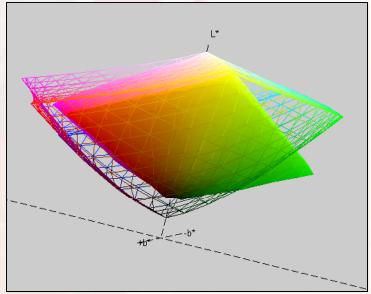






• Comparing Device Gamuts





The process of mapping colors from one device to another is called *Gamut Mapping*







Device Color Model Color Appearance Model

Connection Space

Color Appearance Model

Gamut Mapping Device Color Model



Mark Shaw, Hewlett Packard Company



- The Human Visual System is an integrator
- A colorimetric match only holds if the viewing conditions remain unchanged
- Metamerism is a very important concept
 - Most current imaging systems rely upon the a metameric match
 - Spectral matches would be ideal, but are currently prevented by technological limitations
- Color appearance models enable the communication of color in meaningful terms
- Color Modeling enables one to communicate color consistently