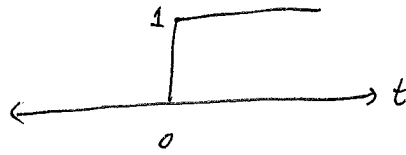


Unit Step and Impulse Functions

Continuous - Time

Unit-step function, $u(t)$

$$u(t) = \begin{cases} 1 & t < 0 \\ 0 & t > 0 \end{cases}$$

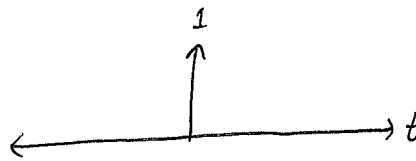


Note the discontinuity @ $t=0$.

Unit impulse function, $\delta(t)$

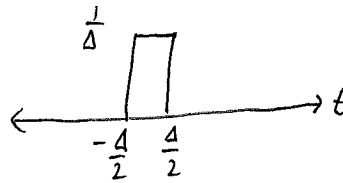
$$\delta(t) = \frac{d}{dt} u(t)$$

$$u(t) = \int_{-\infty}^t \delta(\tau) d\tau$$



Other way to think of $\delta(t)$:

$$\text{Let } \delta_{\Delta}(t) = \begin{cases} \frac{1}{\Delta} & |t| < \frac{\Delta}{2} \\ 0 & \text{o.w.} \end{cases}$$

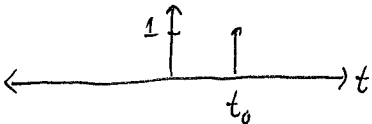
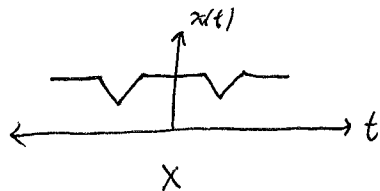


Note: the area of $\delta_{\Delta}(t)$ is always 1.

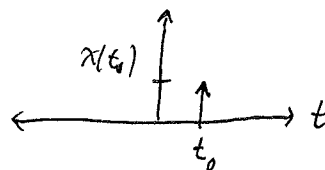
$\delta(t) = \lim_{\Delta \rightarrow 0} \delta_{\Delta}(t)$: It gets infinitesimally ^{narrow} and infinitely tall
But, the area is still 1!

Implications:

$$1) x(t) \delta(t - t_0) = x(t_0) \delta(t - t_0)$$



\Rightarrow



we get a delta centered at t_0
with height $x(t_0)$

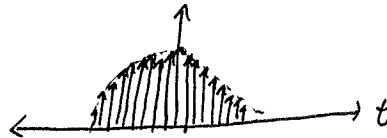
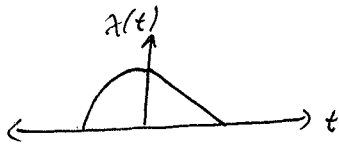
$$2) \int_{-\infty}^{\infty} \delta(t-t_0) dt = 1 \quad \text{since the area of } \delta(t) \text{ is } 1.$$

$$3) \int_{-\infty}^{\infty} x(t) \delta(t-t_0) dt = \int_{-\infty}^{\infty} x(t_0) \delta(t-t_0) dt = x(t_0) \int_{-\infty}^{\infty} \delta(t-t_0) dt \\ = x(t_0)$$

To put it another way:

$$x(t) = \int_{-\infty}^{\infty} x(\tau) \delta(t-\tau) d\tau$$

This means we can think of $x(t)$ as the linear combination of a bunch of shifted and scaled $\delta(t)$'s.

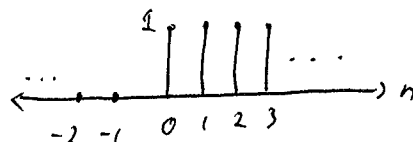


This insight will be important later (impulse response for LTI systems).

Discrete-Time

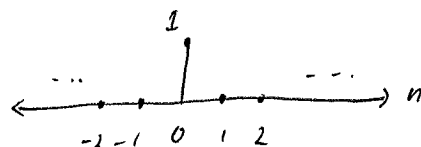
Unit step function, $u[n]$

$$u[n] = \begin{cases} 1 & n \geq 0 \\ 0 & n < 0 \end{cases}$$



Unit delta function, $\delta[n]$

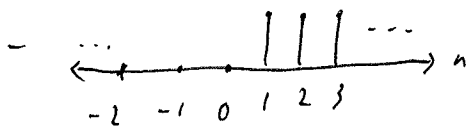
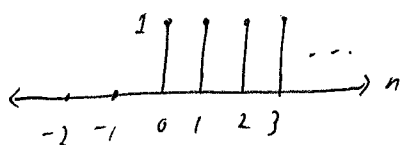
$$\delta[n] = \begin{cases} 1 & n = 0 \\ 0 & n \neq 0 \end{cases}$$



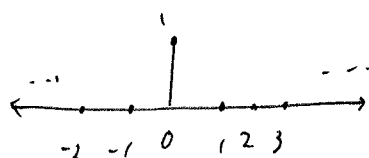
Note that these definitions are much easier to understand.

Relationship of $\delta[n]$ & $u[n]$:

$$\delta[n] = u[n] - u[n-1]$$

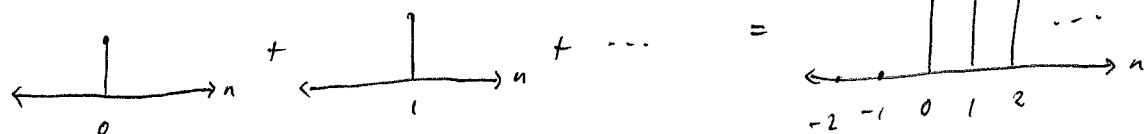


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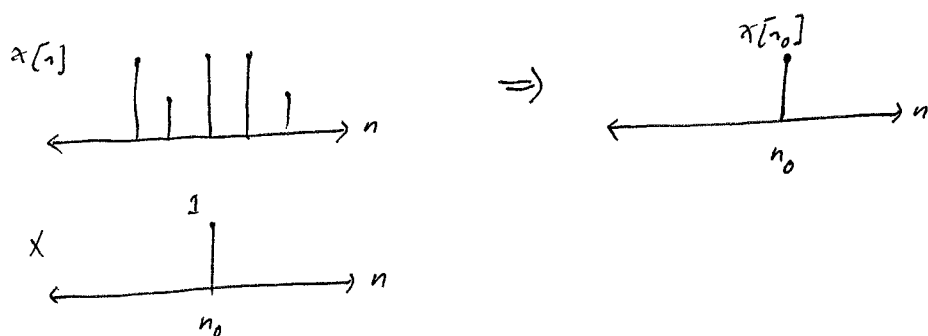
$$u[n] = \sum_{m=-\infty}^n \delta[m]$$

$$= \delta[n] + \delta[n-1] + \dots$$



Implications of $\delta[n]$:

$$1) x[n] \delta[n-n_0] = x[n_0] \delta[n-n_0]$$



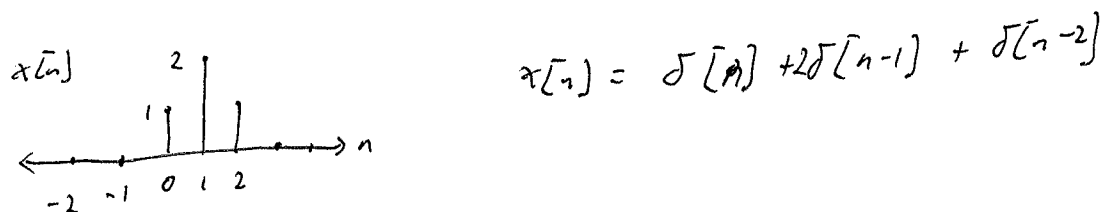
$$2) \sum_{n=-\infty}^{\infty} \delta[n-n_0] = 1$$

$$3) \sum_{n=-\infty}^{\infty} x[n] \delta[n-n_0] = \sum_{n=-\infty}^{\infty} x[n_0] \delta[n-n_0] = x[n_0] \sum_{n=-\infty}^{\infty} \delta[n-n_0] = x[n_0]$$

Put another way:

$$x[n] = \sum_{m=-\infty}^{\infty} x[m] \delta[n-m]$$

This means $x[n]$ really is a bunch of shifted and scaled $\delta[n]$'s.



this is an important concept and we will see it again when we get to discrete-time impulse response of LTI systems.