

(22 pts) 1. Let  $x(t)$  and  $y(t)$  be the input and the output of a continuous-time system, respectively. Answer each of the questions below with either yes or no (no justification needed).

	Yes	No	
If $y(t) = x(2t)$ , is the system causal?	<input type="checkbox"/>	<input checked="" type="checkbox"/>	
If $y(t) = (t + 2)x(t)$ , is the system causal?	<input type="checkbox"/>	<input checked="" type="checkbox"/>	outside $x(t)$
If $y(t) = x(-t^2)$ , is the system causal?	<input checked="" type="checkbox"/>	<input type="checkbox"/>	$t = \pm \sqrt{2} \Rightarrow$ outside $x(t)$
If $y(t) = x(t) + t - 1$ , is the system memoryless?	<input checked="" type="checkbox"/>	<input type="checkbox"/>	
If $y(t) = x(t^2)$ , is the system memoryless?	<input type="checkbox"/>	<input checked="" type="checkbox"/>	-
If $y(t) = x(t/3)$ , is the system stable?	<input checked="" type="checkbox"/>	<input type="checkbox"/>	
If $y(t) = tx(t/3)$ , is the system stable?	<input type="checkbox"/>	<input checked="" type="checkbox"/>	
If $y(t) = \int_{-\infty}^t x(\tau) d\tau$ , is the system stable?	<input checked="" type="checkbox"/>	<input type="checkbox"/>	plugin
If $y(t) = \sin(x(t))$ , is the system time invariant?	<input type="checkbox"/>	<input checked="" type="checkbox"/>	
If $y(t) = u(t) * x(t)$ , is the system LTI?	<input checked="" type="checkbox"/>	<input type="checkbox"/>	
If $y(t) = (tu(t)) * x(t)$ , is the system linear?	<input checked="" type="checkbox"/>	<input type="checkbox"/>	

$$= \int tu(t) * x(t)$$

||

(15 pts) 2. An LTI system has unit impulse response  $h(t) = u(t+2)$ . Compute the system's response to the input  $x(t) = e^{-t}u(t)$ . (Simplify your answer until all  $\sum$  signs disappear.)

$$y(t) = x(t) * h(t) = \int_{-\infty}^{\infty} x(\tau) h(t-\tau) d\tau$$

$$= \int_{-\infty}^{\infty} e^{-\tau} u(\tau) u(t-\tau+2) d\tau$$

↓

but  $u(\tau) = 0$   
when  $\tau < 0$

$$= \int_0^{\infty} e^{-\tau} u(t-\tau+2) d\tau u(t)$$

but  $u(t-\tau+2) = 0$

when  $t-\tau+2 < 0$

$$\Leftrightarrow -\tau < -t-2$$

$$\Leftrightarrow \tau > t+2$$

$$= \int_0^{t+2} e^{-\tau} d\tau \quad u(t)$$

~~u(t)~~

↑  
 $u(t+2)$

$$= -e^{-\tau} \Big|_0^{t+2} u(t) = -e^{-t-2} + 1 u(t)$$

distribute -

↑ Please organize your answer so one can understand your computation easily. Like this it is very hard to follow. In particular, you must write "=" when you mean "equal".

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(15 pts) 3. Compute the energy and the power of the signal  $x(t) = \frac{3e^{jt}}{1+j} = \frac{3}{1+j} e^{jt}$

$$E_{\infty} = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

$$E_{\infty} = \int_{-\infty}^{\infty} 1^2 dt = \infty$$

$$P_{\infty} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

$$= \frac{1}{2T} \int_{-T}^T 1 dt = \frac{1}{2T} 2T = 1$$

$$E_{\infty} = \int_{-\infty}^{\infty} |x(t)|^2 dt$$

$$|x(t)| = \left| \frac{3e^{jt}}{1+j} \right|$$

$$= \frac{3 |e^{jt}|}{|1+j|} = \frac{3}{\sqrt{2}}$$

$$P_{\infty} = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T \frac{9}{2} dt$$

$$= \lim_{T \rightarrow \infty} \frac{1}{2T} \frac{9}{2} 2T = \frac{9}{2}$$

$$E_{\infty} = \infty$$

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(15 pts) 4. Compute the coefficients  $a_k$  of the Fourier series of the signal  $x(t)$  periodic with period  $T = 4$  defined by

$$x(t) = \begin{cases} \sin(\pi t), & 0 \leq t \leq 2 \\ 0, & 2 < t \leq 4 \end{cases}$$

(Simplify your answer as much as possible.)

$$T=4, \quad \sin(\pi t) = \frac{e^{j\pi t} - e^{-j\pi t}}{2j}$$

$$a_k = \frac{1}{T} \int_0^T x(t) e^{-jk \left(\frac{T}{T}\right) t} dt$$

$$= \int_0^2 \sin(\pi t) e^{-jk t} dt = \frac{e^{j\pi/2}}{2j} - \frac{e^{-j\pi/2}}{2j}$$

$$\frac{2\pi}{4} = \pi/2$$

$$a_0 = \frac{1}{T} \int_0^T x(t) dt$$

$$a_4 = \frac{1}{2j} \quad a_{-4} = -\frac{1}{2j}$$

5. A discrete-time system is such that when the input is one of the signals in the left column, then the output is the corresponding signal in the right column:

input	output
$x_0[n] = \delta[n]$	$\rightarrow y_0[n] = \delta[n - 1]$ ,
$x_1[n] = \delta[n - 1]$	$\rightarrow y_1[n] = 4\delta[n - 2]$ ,
$x_2[n] = \delta[n - 2]$	$\rightarrow y_2[n] = 9\delta[n - 3]$ ,
$x_3[n] = \delta[n - 3]$	$\rightarrow y_3[n] = 16\delta[n - 4]$ ,
$\vdots$	
$x_k[n] = \delta[n - k]$	$\rightarrow y_k[n] = (k + 1)^2\delta[n - (k + 1)]$ for any integer $k$ .

(10 pts) a) Can this system be time-invariant? Explain.

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$$x[n] \rightarrow \boxed{\text{sys}} \xrightarrow{x[n] = \delta[n-t]} \boxed{\text{TD}} \rightarrow z[n] = y[n-k]$$

$$x[n] \rightarrow \boxed{\text{TD}} \xrightarrow{x[n] = \delta[n-n_0]} \boxed{\text{sys}} \rightarrow z[n] = y[n-n_0]$$

Not TI

$$y[n] = \delta[n-k+n_0]$$

$$y[n] = \delta[n-k-n_0]$$

)  $\neq$

(10 pts) b) Assuming that this system is linear, what input  $x[n]$  would yield the output  $y[n] = u[n - 1]$ ?

$$x[n] = \delta[n]$$

$$k=0 \quad y[n] = (k+1)^2 \delta[n - (k+1)]$$

0

$$y[n] = (0+1)^2 \delta[n - (0+1)]$$

$$y[n] = 1 \cdot \delta[n - 1]$$