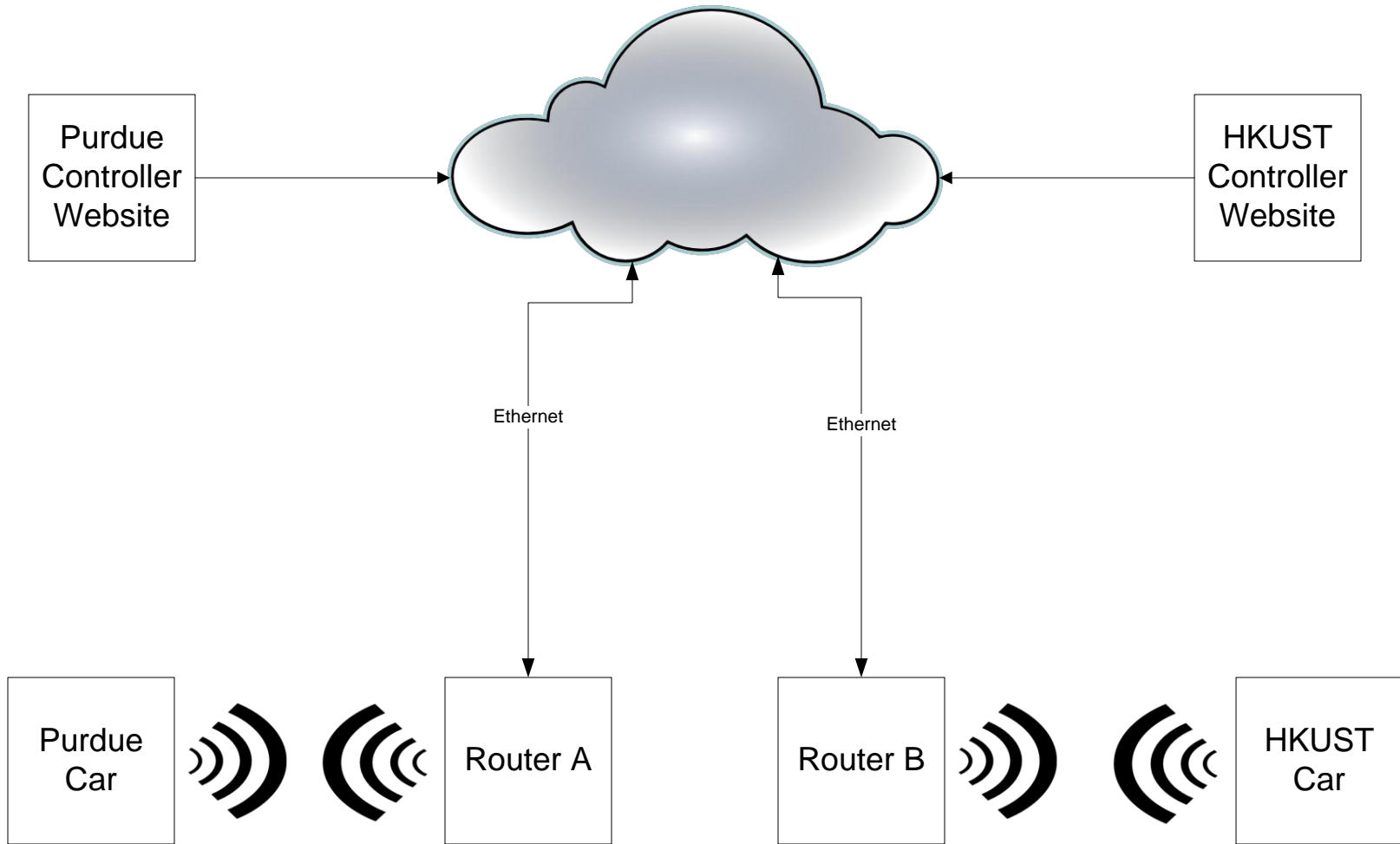
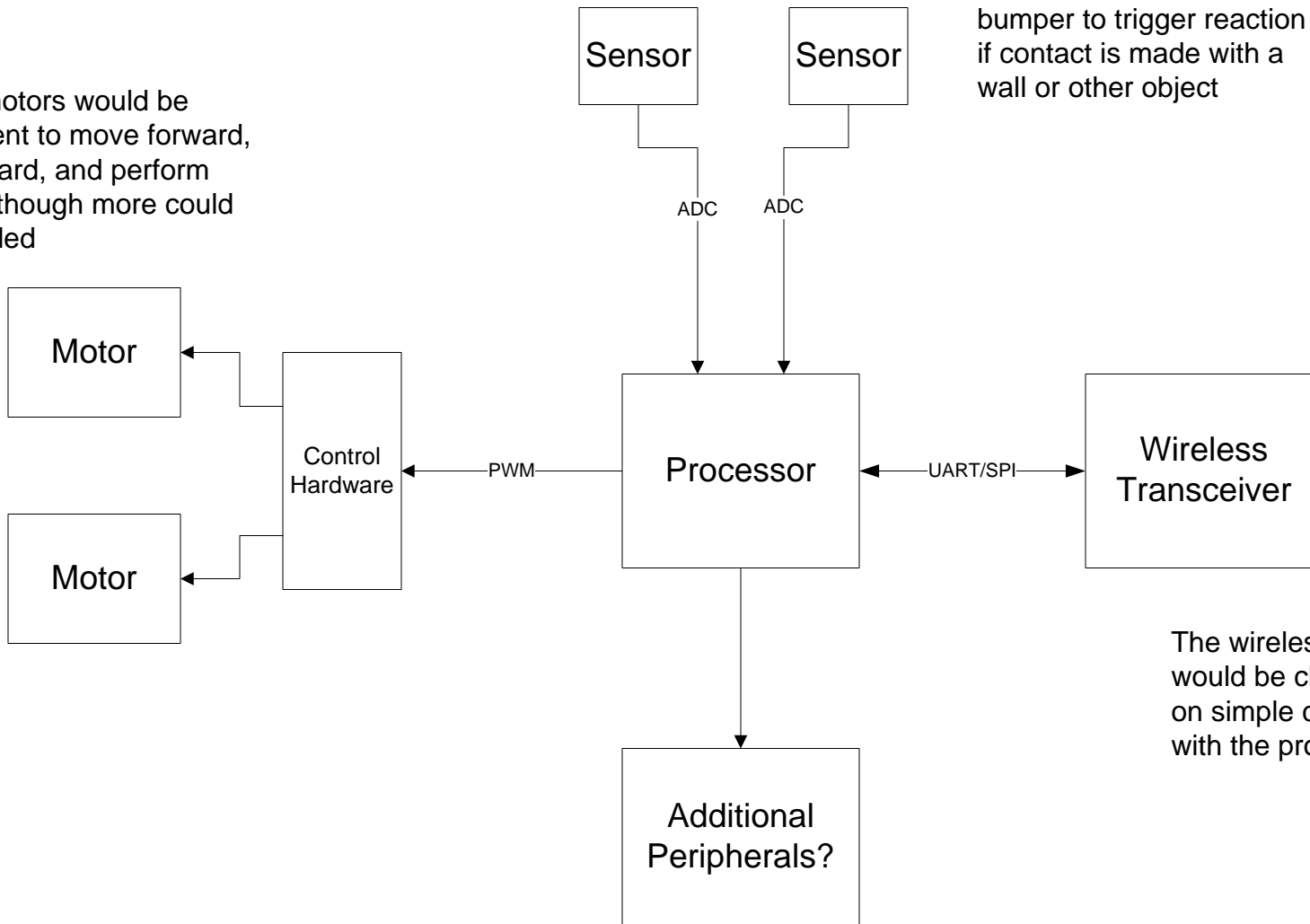


High Level Interconnection



Simplified Layout of Vehicle Control and Peripherals

Two motors would be sufficient to move forward, backward, and perform turns, though more could be added



Sensors could be IR or even pushbuttons on a bumper to trigger reaction if contact is made with a wall or other object

The wireless module would be chosen based on simple communication with the processor

Once the more necessary features have been implemented, more peripherals could be added.