Fat When an LTI System is causal, then

corollary - output of cauch lines, time-invariat system is

y[n] = 8 X[k]n[n-k]

Stability:

Fact when the system is LTI , it is stable iff. Elhand is finite

why? assume
$$x(t)$$
 is bounded i.e. $|x[n]| < \epsilon$

$$|y[n]-|\tilde{z}|$$
 xcm ncn-ro) = $|\tilde{z}|$ h[r] x[n-r] = $|\tilde{z}|$ | h[r]x[n-r] =

Tso just make sure this is bunded E is bunded by definition

Q: An LTI system has han = δ Cn) show that the system is stable so $\frac{2}{50}$ δ Cn] = 1 so stable

a Show that if yeth = S x(T) of the system is worldle

Hint: observe that h(D= UCt)

The system is UTI so all we need to check is it is if it is finite,

To set h(t), poly S(t) into output formula?

y(t) = \$560 dr = v(t)

5/nGH) or = 5/oct) dt = 5 oct) ct = 20, so it is unstable

Show LT1:1) 70 show Inecusty: +

GX(H) +bx(H) -> SAX(H) +bx(H)

= G\$ X1(H) 75\$ X(H) AT

= GY, (H) + by(H)

2) Time Invariance: $x(t) = \sqrt{TD} = z(t) = x(t-1_0) = \sqrt{D} = \sqrt{z}(t)dr = \sqrt{x(t-1_0)}dr$ $x(t) = \sqrt{D} = y(t) = \sqrt{x(t)}dr = \sqrt{D} = z(t) = y(t-1_0) = \sqrt{x(t)}dr$ $\text{let } \theta = \sqrt{-t_0} + \text{then } d\theta = dr = \sqrt{x(t)}d\theta$

who is some as SXDDAr